Fast Multivariate Multipoint Evaluation

Based on joint works with various subsets of V Bhargava, S Ghosh, Z Guo, P Harsha, S Herdade, C K Mohapatra, R Saptharishi, C Umans

Input

- An m-variate polynomial f with degree at most (d-1) in each variable over a field K, as a list of coefficients
- N points $\alpha_1, \alpha_2, ..., \alpha_N \in \mathbf{K}^{\mathbf{m}}$

Output

- Evaluation of f on $\alpha_1,\alpha_2,\,\ldots,\,\,\alpha_N$

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Input: $(d^m + Nm)$ field elements

Naïve algorithm

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Roughly (Nmd^m) field operations in total

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Can we do this faster ?

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Evaluate f on \alpha_i
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Roughly (Nmd^m) field operations in total When $N = d^m$, quadratic in the input size

Can we do this faster ?

In particular, is there an algorithm that runs in linear time in the input size ?

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Various versions: nearly linear time in the output size, input points with small absolute value, computing approximations of the evaluations, or count field operations only

Approximate multipoint evaluation (rationals/reals/complexes)

Input

- An m-variate polynomial f with degree at most (d-1) in each variable over $\underline{rational}$ $\underline{numbers}$, as a list of coefficients
- N points $\alpha_1, \alpha_2, \ldots, \ \alpha_N \in Q^{\mathbf{m}}$, from the unit cube
- <u>Accuracy parameter t</u>

Output

- Rational numbers $\beta_1, \beta_2, ..., \beta_N$ such that $|f(\alpha_i) - \beta_i| < 1/2^t$

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- Many direct and natural applications fast modular composition, univariate polynomial factorization over finite fields, generating irreducible polynomials, computing minimal polynomials, data structures for polynomial evaluation,
- Current fastest algorithms for all these problems go via fast multipoint evaluation

What do we know ?

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Input is specified via (N + d) field elements

For structured set of input points

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• [Borodin-Moenck, 1974] An algorithm with $(N + d)^{1+o(1)}$ field operations

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- [Borodin-Moenck, 1974] An algorithm with $(N + d)^{1+o(1)}$ field operations
- a very clever and neat application of FFT

For an arbitrary set of input points

- [Moroz, 2019] An nearly linear time algorithm for approximate univariate MME
- Based on known algorithms for approximate FFT + beautiful geometric ideas

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• when $\alpha_1, \alpha_2, ..., \alpha_N \in \mathbf{K}$ form a product set, i.e., $\{\alpha_1, \alpha_2, ..., \alpha_N\} = S_1 \times S_2 \times \cdots \times S_m$, for $S_i \subseteq \mathbf{K}$

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 an easy nearly linear time algorithm – induction on the number of variables

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- an easy nearly linear time algorithm induction on the number of variables
- uses the univariate case as the base case

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- based on faster rectangular matrix multiplication

[Umans, 2008]

- 1. char(**K**) is less than $d^{o(1)}$
- 2. number of variables (m) is less than $d^{o(1)}$

[Umans, 2008]

A nearly linear time algorithm for multivariate multipoint evaluation when

- 1. char(**K**) is less than $d^{o(1)}$
- 2. number of variables (m) is less than $d^{o(1)}$

[Kedlaya, Umans, 2008]

- **1. K** is any finite field
- 2. number of variables (m) is less than $d^{o(1)}$

[Bjorklund, Kaski, Williams, 2019]

- 1. |K| is small
- 2. |K|-1 has small divisors

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A nearly linear time algorithm for multivariate multipoint evaluation when

- 1. **|K**| is small
- 2. |K|-1 has small divisors

Not a polynomial time algorithm, since the running time depends polynomially (and not polylogarithmically) on the field size Nevertheless, happens to be very useful for one of our results

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This is the question that we study in our work and focus of rest of the talk.

[Bhargava, Ghosh, K., Mohapatra, 2021]

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A nearly linear time algorithm for multivariate multipoint evaluation when

- 1. char(**K**) is less than $d^{o(1)}$
- 2. K is of size at most exp(exp(exp(...exp(d))))

(tower of fixed height)

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A nearly linear time algorithm for multivariate multipoint evaluation when

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- 2. number of variables (m) is less than $d^{o(1)}$

(degree d is asymptotically growing)

[Ghosh, Harsha, Herdade, K, Saptharishi, 2023]

A nearly linear time algorithm for <u>approximate</u> multivariate multipoint evaluation.

• Running time is $((Nm + d^m)t)^{1+o(1)}$

(degree d is asymptotically growing)

In particular

No nearly linear time algorithm for multivariate multipoint evaluation when

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Nearly linear time algorithm for multivariate multipoint evaluation over all finite fields, for growing d, and all m

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Our results

Nearly linear time algorithm for multivariate multipoint evaluation over all finite fields, for growing d, and all m

Nearly linear time algorithm for approximate multivariate multipoint evaluation over rationals, reals, complex numbers, for growing d, and all m

In summary

	Field Size	Characteristic	Number of variables	Algebraic vs non- algebraic
Umans	Finite	char(K) < $d^{o(1)}$	$m < d^{o(1)}$	Algebraic
Kedlaya-Umans	Finite	All finite fields	$m < d^{o(1)}$	Non-algebraic
Bhargava-Ghosh-K- Mohapatra	Not-too-large	char(K) < $d^{o(1)}$	No constraint	Algebraic
Bhargava-Ghosh- Guo-K-Umans	Finite	All finite fields	No constraint	Non-algebraic
Ghosh-Harsha- Herdade-K- Saptharishi	Infinite	Rationals, Reals, Complex numbers	No constraint	Non-algebraic (approximate MME)

Applications ?

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 Two non-blackbox applications from the algorithm over finite fields of small characteristic – algebraic data structures for polynomial evaluation, upper bounds on the rigidity of Vandermonde matrices

Data structures for polynomial evaluation
• K – finite field of size q

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- Resources
 - Space complexity: amount of memory needed for storage in the worst case
 - Query complexity: number of cells/bits in the memory needed to access queries in the worst case

The *first* construction

• Data: $f(x) = f_0 + f_1 \cdot x + \dots + f_{d-1} x^{d-1}$

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- optimal
- not great

The *second* construction

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A natural question

Is there a construction that achieves the best of both these worlds ? Space complexity: $(d \cdot \log q)^{1+o(1)}$ Query complexity: $(\log q)^{1+o(1)}$

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[Kedlaya-Umans, 2008] Sort of!

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Query complexity: $poly(log d) \cdot (log q)^{1+o(1)}$

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So, this *almost* answers this question!

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Algebraic data structures: all the associated underlying algorithms are algebraic

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- naïve algorithm for multipoint evaluation, Fast Fourier Transform, both the simple data structures for polynomial evaluation are algebraic
- algorithm of Kedlaya-Umans for multipoint evaluation is non-algebraic uses things like bit operations, lifts the problem from the underlying field to over integers
- algebraic algorithms might be more aesthetic, could be useful when working with arithmetic models of computation

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[Miltersen, 1995]

If q > exp(d), then essentially no algebraic data structure for polynomial evaluation better than the trivial solution of storing all coefficients.

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Is that even possible ?

[Miltersen, 1995]

If q > exp(d), then essentially no algebraic data structure for polynomial evaluation better than the trivial solution of storing all coefficients.

Conjectured that the same should hold even for smaller fields.

A corollary

[Bhargava, Ghosh, K., Mohapatra, 2021]

A data structure for polynomial evaluation with nearly linear space and sublinear query complexity, provided

1. char of the field is small

2. q < quasipoly(d)

(Input size: $d \cdot \log q$ bits)

(r,s)-rigid matrices

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V \neq L + S, where rank(L) < r, sparsity(S) < s
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Many popular candidates – Hadamard, Discrete Fourier Transform, Vandermonde matrices
Matrix Rigidity

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No sufficiently strong lower bounds

[Alman, Williams, 2016]

Hadamard matrices are not sufficiently rigid

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[Dvir, Liu, 2019]

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And, some more – Alman, Dvir-Edelman, Kivva....

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Rigidity upper bounds for general Vandermonde matrices remains open

A corollary

[Bhargava, Ghosh, K., Mohapatra, 2021]

Vandermonde matrices are not sufficiently rigid, when 1. char of the field is small 2. q < quasipoly(dimension)

Theorem

A nearly linear time algorithm for multivariate multipoint evaluation when

- 1. char(**K**) is less than $d^{o(1)}$
- 2. K is of size at most exp(exp(exp(...exp(d))))

(tower of fixed height)

Input

- An m-variate polynomial f with degree at most (d-1) in each variable over a field K, as a list of coefficients
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• Preprocessing phase: independent of the evaluation points $\alpha_1, \alpha_2, ..., \alpha_N$

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Two phases of the algorithm

- Preprocessing phase: independent of the evaluation points $\alpha_1, \alpha_2, ..., \alpha_N$
- Local computation phase: depend on $\alpha_1, \alpha_2, ..., \alpha_N$, and earlier computation

Preprocessing phase

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2. Evaluate f on all points of S

Local computation

• have an $\alpha \in \mathbf{K}^m$, want to compute $f(\alpha)$ fast, using info from the previous step



α

- •



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- let $C_{\alpha}(y) = (r_{\alpha,1}(y), r_{\alpha,2}(y), ..., r_{\alpha,m}(y))$ be the low degree curve through α , with large intersection with S; each $r_{\alpha,i}(y)$ is a low degree polynomial

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- let $g(t)=f(r_{\alpha,1}\big(y\big),r_{\alpha,2}\big(y\big),\ ...,r_{\alpha,m}\big(y\big))$ be the restriction of the polynomial f on the curve $C_{\alpha}\big(y\big)$

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• once, we have g, can recover $g(u) = f(\alpha)$



α

- •
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- $\cdot |S| < \left(pdm \cdot \log_p |K| \right)^m$
- $\deg(C_{\alpha}) < \log_{\mathbf{p}} |\mathbf{K}|$
- $|C_{\alpha} \cap S| > \log_{p} |\mathbf{K}| \cdot dm > deg(C_{\alpha}) \cdot dm$

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- to compensate, need stronger preprocessing phase, and a more complicated local computation step

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running time -
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- then, use this additional info, together with values of f on S to do interpolation











- First compute f on curves through simpler points β , γ using the previous algorithm
- Then, use the values of f on S, and curves through $\beta,~\gamma$ to compute f on C_{α}

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- one simpler and shorter to describe, but not entirely elementary
- crucially uses a result of Bombieri-Vinogradov about the density of primes in an arithmetic progression
- essentially, both improve some of the bottlenecks in Kedlaya-Umans using ideas from the small characteristic case and BKW19 in slightly different ways

Open Questions

- An algebraic algorithm over finite fields ?
- An algorithm (or an algebraic circuit) over infinite fields (complex numbers) ?
- More applications ?
- What about faster algorithms for other related problems ? e.g. multivariate interpolation ?
- What about the case of constant d ? e.g. multilinear polynomials ?

Thank You!